FIN1531
5V LVDS 4-Bit High Speed Differential Driver

General Description
This quad driver is designed for high speed interconnects utilizing Low Voltage Differential Signaling (LVDS) technology. The driver translates 5V TTL/CMOS signal levels to LVDS levels with a typical differential output swing of 350 mV which provides low EMI at ultra low power dissipation even at high frequencies. This device is ideal for high speed transfer of clock and data.

The FIN1531 can be paired with its companion receiver, the FIN1532, or with any other Fairchild LVDS receiver.

Features
- Greater than 400Mbs data rate
- 5V power supply operation
- 400ps max differential pulse skew
- 2.0ns maximum propagation delay
- Low power dissipation
- Power-Off protection
- Meets or exceeds the TIA/EIA-644 LVDS standard
- Pin compatible with equivalent RS-422 and PECL devices
- 16-Lead SOIC and TSSOP packages save space

Ordering Code:

<table>
<thead>
<tr>
<th>Order Number</th>
<th>Package Number</th>
<th>Package Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>FIN1531M</td>
<td>M16A</td>
<td>16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150” Narrow</td>
</tr>
<tr>
<td>FIN1531MTC</td>
<td>MTC16</td>
<td>16-Lead Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide</td>
</tr>
</tbody>
</table>

Function Table

<table>
<thead>
<tr>
<th>Input</th>
<th>EN</th>
<th>EN</th>
<th>D IN</th>
<th>D OUT+</th>
<th>D OUT−</th>
</tr>
</thead>
<tbody>
<tr>
<td>H</td>
<td>X</td>
<td>H</td>
<td>H</td>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>H</td>
<td>X</td>
<td>L</td>
<td>L</td>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>H</td>
<td>X</td>
<td>OPEN</td>
<td>L</td>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>X</td>
<td>L</td>
<td>H</td>
<td>H</td>
<td>L</td>
<td>L</td>
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<tr>
<td>X</td>
<td>L</td>
<td>L</td>
<td>L</td>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>X</td>
<td>L</td>
<td>OPEN</td>
<td>L</td>
<td>H</td>
<td>L</td>
</tr>
<tr>
<td>L</td>
<td>H</td>
<td>X</td>
<td>Z</td>
<td>Z</td>
<td></td>
</tr>
</tbody>
</table>

EN = HIGH Logic Level
L = LOW Logic Level
X = Don’t Care
Z = High Impedance

Connection Diagram

Pin Descriptions

<table>
<thead>
<tr>
<th>Pin Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>D IN1, D IN2, D IN3, D IN4</td>
<td>5V TTL/CMOS Data Input</td>
</tr>
<tr>
<td>D OUT1+, D OUT2+, D OUT3+, D OUT4+</td>
<td>Non-inverting LVDS Output</td>
</tr>
<tr>
<td>D OUT1−, D OUT2−, D OUT3−, D OUT4−</td>
<td>Inverting LVDS Output</td>
</tr>
<tr>
<td>EN</td>
<td>Driver Enable Pin</td>
</tr>
<tr>
<td>EN</td>
<td>Inverting Driver Enable Pin</td>
</tr>
<tr>
<td>V CC</td>
<td>Power Supply</td>
</tr>
<tr>
<td>GND</td>
<td>Ground</td>
</tr>
</tbody>
</table>
### Absolute Maximum Ratings (Note 1)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage ((V_{CC}))</td>
<td>−0.5V to +6V</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>DC Input Voltage ((V_{IN}))</td>
<td>−0.5V to +6V</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>DC Output Voltage ((V_{OUT}))</td>
<td>−0.5V to +6V</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Driver Short Circuit Current ((I_{OSD}))</td>
<td>Continuous</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Storage Temperature Range ((T_{STG}))</td>
<td>−65°C to +150°C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Max Junction Temperature ((T_J))</td>
<td>150°C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Lead Temperature ((T_L))</td>
<td>260°C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>ESD (Human Body Model)</td>
<td>≥ 8000V</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>ESD (Machine Model)</td>
<td>≥ 4000V</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### DC Electrical Characteristics

Over supply voltage and operating temperature ranges, unless otherwise specified.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Conditions</th>
<th>Min</th>
<th>Typ (Note 2)</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>(V_{OD})</td>
<td>Output Differential Voltage</td>
<td>(RL = 100\Omega), driver enabled, See Figure 1</td>
<td>250</td>
<td>350</td>
<td>450</td>
<td>mV</td>
</tr>
<tr>
<td>(\Delta V_{OD})</td>
<td>Magnitude Change from Differential LOW-to-HIGH</td>
<td>(RL = 100\Omega), driver enabled, See Figure 1</td>
<td>25</td>
<td></td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td>(V_{OS})</td>
<td>Offset Voltage</td>
<td></td>
<td>1.125</td>
<td>1.25</td>
<td>1.375</td>
<td>V</td>
</tr>
<tr>
<td>(\Delta V_{OS})</td>
<td>Magnitude Change from Differential LOW-to-HIGH</td>
<td>(RL = 100\Omega), driver enabled, See Figure 1</td>
<td>25</td>
<td></td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td>(I_{OFF})</td>
<td>Power Off Output Current</td>
<td>(V_{CC} = 0V, V_{OUT} = 5.5V)</td>
<td>50</td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>(I_{OS})</td>
<td>Short Circuit Output Current</td>
<td>(V_{OUT} = 0V, Driver Enabled)</td>
<td></td>
<td></td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>(V_{IH})</td>
<td>Input HIGH Voltage</td>
<td></td>
<td>2.0</td>
<td>(V_{CC})</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>(V_{IL})</td>
<td>Input LOW Voltage</td>
<td></td>
<td>GND</td>
<td>0.8</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>(I_{N})</td>
<td>Input Current</td>
<td>(V_{IN} = 0V) or (V_{CC})</td>
<td>≤20</td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>(I_{OFF})</td>
<td>Power-OFF Input Current</td>
<td>(V_{CC} = 0V, V_{IN} = 5.5V)</td>
<td>50</td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>(I_{OZ})</td>
<td>Disabled Output Leakage Current</td>
<td>(EN = 0.8V, EN = 2.0V, V_{OUT} = 0V or 7V)</td>
<td>≤20</td>
<td></td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>(V_{IK})</td>
<td>Input Clamp Voltage</td>
<td>(I_{IK} = -18mA)</td>
<td>−1.5</td>
<td>−0.8</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>(I_{CC})</td>
<td>Power Supply Current</td>
<td>No Load, (V_{IN} = 0V) or (V_{CC}), Driver Enabled</td>
<td>3.3</td>
<td>6</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(RL = 100\Omega), Driver Disabled</td>
<td>3.4</td>
<td>6</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(RL = 100\Omega, V_{IN} = 0V) or (V_{CC}), Driver Enabled</td>
<td>18</td>
<td>26</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(C_{IN})</td>
<td>Input Capacitance</td>
<td></td>
<td>7</td>
<td></td>
<td></td>
<td>pF</td>
</tr>
<tr>
<td>(C_{OUT})</td>
<td>Output Capacitance</td>
<td></td>
<td>4.5</td>
<td></td>
<td></td>
<td>pF</td>
</tr>
</tbody>
</table>

**Note 2:** All typical values are at \(T_A = 25°C\) and with \(V_{CC} = 5.5V\).
## AC Electrical Characteristics

Over supply voltage and operating temperature ranges, unless otherwise specified

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Conditions</th>
<th>Min (Note 3)</th>
<th>Typ</th>
<th>Max (Note 3)</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>τ_{PLHD}</td>
<td>Differential Propagation Delay</td>
<td>R_L = 100 Ω, C_L = 10 pF, See Figure 2 and Figure 3 (Note 7)</td>
<td>0.5</td>
<td>1.4</td>
<td>2.0</td>
<td>ns</td>
</tr>
<tr>
<td>τ_{PHLD}</td>
<td>Differential Propagation Delay</td>
<td></td>
<td>0.5</td>
<td>1.4</td>
<td>2.0</td>
<td>ns</td>
</tr>
<tr>
<td>τ_{LHD}</td>
<td>Differential Output Rise Time (20% to 80%)</td>
<td></td>
<td>0.6</td>
<td>0.8</td>
<td>1.2</td>
<td>ns</td>
</tr>
<tr>
<td>τ_{HLD}</td>
<td>Differential Output Fall Time (80% to 20%)</td>
<td></td>
<td>0.6</td>
<td>0.8</td>
<td>1.2</td>
<td>ns</td>
</tr>
<tr>
<td>τ_{SKP}</td>
<td>Pulse Skew [τ_{PH} - τ_{PL}]</td>
<td></td>
<td></td>
<td>0.4</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>τ_{SKPH}</td>
<td>Channel-to-Channel Skew (Note 4)</td>
<td></td>
<td></td>
<td>0.3</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>τ_{SKPP}</td>
<td>Part-to-Part Skew (Note 5)</td>
<td></td>
<td></td>
<td>1.0</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>f_{MAX}</td>
<td>Maximum Frequency (Note 6)</td>
<td></td>
<td>200</td>
<td></td>
<td>250</td>
<td>ns</td>
</tr>
<tr>
<td>t_{ZHD}</td>
<td>LVTTL Output Enable Time from Z to HIGH</td>
<td>R_L = 100 Ω, C_L = 10 pF, See Figure 4 and Figure 5 (Note 7)</td>
<td></td>
<td>5.0</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>t_{ZLD}</td>
<td>LVTTL Output Enable Time from Z to LOW</td>
<td></td>
<td>5.0</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>t_{HZD}</td>
<td>LVTTL Output Disable Time from HIGH to Z</td>
<td></td>
<td>5.0</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>t_{LZD}</td>
<td>LVTTL Output Disable Time from LOW to Z</td>
<td></td>
<td>5.0</td>
<td></td>
<td></td>
<td>ns</td>
</tr>
</tbody>
</table>

**Note 3:** All typical values are at T_A = 25°C and with V_{CC} = 5V.

**Note 4:** τ_{SK(LH)}, τ_{SK(HL)} is the skew between specified outputs of a single device when the outputs have identical loads and are switching in the same direction.

**Note 5:** τ_{SK(PP)} is the magnitude of the difference in propagation delay times between any specified terminals of two devices switching in the same direction (either LOW-to-HIGH or HIGH-to-LOW) when both devices operate with the same supply voltage, same temperature, and have identical test circuits.

**Note 6:** f_{MAX} Criteria: Input τ_{IN} < 1 ns, 0V to 3V, 50% Duty Cycle; Output V_{OD} > 250 mV, 45% to 55% Duty Cycle; all output channels switching in phase.

**Note 7:** Test Circuits in Figure 2 and Figure 4 are simplified representations of test fixture and DUT loading.
FIGURE 1. Differential Driver DC Test Circuit

Note A: Input pulses have frequency = 10 MHz, \( t_R \) or \( t_F \) = 1 ns

Note B: \( C_L \) includes all probe and jig capacitances

FIGURE 2. Differential Driver Propagation Delay and Transition Time Test Circuit

Note A: Input pulses have the following characteristics:
Frequency = 10 MHz, \( t_R \) or \( t_F \) = 1 ns

Note B: \( C_L \) includes probe and jig capacitances

FIGURE 3. AC Waveforms

FIGURE 4. Differential Driver Enable and Disable Test Circuit

Note A: Input pulses have the following characteristics:
Frequency = 10 MHz, \( t_R \) or \( t_F \) = 1 ns

Note B: \( C_L \) includes probe and jig capacitance

FIGURE 5. Enable and Disable AC Waveforms
Physical Dimensions inches (millimeters) unless otherwise noted

16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow
Package Number M16A
Physical Dimensions inches (millimeters) unless otherwise noted (Continued)

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2. A critical component in any component of a life support device or system whose failure to perform can be rea-sonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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